

Investigation Of Motion Analysis Techniques For Animation Evaluation And Improvement

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Abstract.

The assessment and enhancement of animation quality heavily relies on motion analysis. This study looks into several motion analysis methods for assessing and improving animation. The goal is to find practical methods that may be used to evaluate the expressiveness, fluidity, and realism of animated characters and then enhance their motion. The study starts off with a thorough literature review that examines a variety of motion analysis methods used in the world of animation. These methods comprise motion capture, position estimation, key frame analysis, physics-based simulation, and machine learning-based methods. Each technique's benefits and drawbacks are analysed, as well as how well it works with various types of animation and settings. As part of the research process, motion data is gathered from a variety of animated sequences, and the identified motion analysis methodologies are then used to evaluate the data. Performance indicators including joint angles, timing, and trajectory are assessed and contrasted with predetermined benchmarks or data on human motion. The visual appeal and plausibility of the animations are also evaluated through perception research involving human viewers. Recommendations are offered for enhancing animation workflows and techniques based on the findings. These suggestions include improving the present motion capture pipelines, introducing machine learning methods for motion prediction and synthesis, and incorporating more precise physics-based models.

I. Introduction

Techniques for motion analysis are essential for evaluating and enhancing animation. There is an increasing need for unbiased methods to evaluate the calibre and realism of animated motion as the field of animation develops. Animation studios, video game designers, and visual effects artists work hard to produce realistic animations that captivate viewers and improve the visual experience as a whole.

In the past, directors and animators used their subjective judgements to evaluate animation. Although these professional judgements are valuable, they are subject to individual biases. Additionally, it gets harder for human judges to accurately pick out flaws and discern small nuances as animations become more intricate and lifelike. Techniques for motion analysis have a number of benefits over subjective assessments. First of all, they offer exact and quantifiable data that enables unbiased comparisons between various animations or iterations. Second, by highlighting specific problem areas, these strategies let animators concentrate their efforts on improving particular facets of motion. The animation production process can be made more efficient with the aid of motion analysis tools by saving time and money on trial-and-error iterations. This study intends to investigate and assess various motion analysis methods applied to the evaluation and enhancement of animation. We aim to get a thorough understanding of the numerous tools, methods, and methodologies used in motion analysis by studying

the available literature. We'll look into how these methods have been used in various animation fields, such as video games, virtual reality, and movies, and evaluate how well they work at spotting motion-related problems and making suggestions for solutions.

The difficulties and limitations of motion analysis techniques will also be covered in this inquiry. These methods have limitations even though they offer insightful information. The applicability and accessibility of motion analysis in real-world animation can be impacted by variables like computing complexity, data collecting and processing, and the requirement for qualified analysts.

II. Review of Literature

In the domains of computer vision and animation, hand motion capture and tracking have been intensively investigated [1]. Traditional methods, such wearing gloves or employing input devices, can be costly, inconvenient, and difficult to use. Methods that rely on hand annotations or extremely restricted surroundings are also viewed negatively. Vision-based hand tracking has become a practical, inexpensive, and non-intrusive solution to these problems. Vision-based techniques provide a more adaptable solution compared to database- and appearance-based methods, which demand a large amount of training data.

While investigating high-dimensional landscapes with many degrees of freedom requires model-based techniques, which can be computationally taxing. Like any vision system, occlusions provide difficulties for vision-based hand tracking. However, it is essential to build a system that makes use of inexpensive and accessible components, as well as a simple configuration, taking into account the goal of giving small animation studios a useful tool [2]. According to these specifications, the research proposal proposes to create a hand motion capture and tracking system that satisfies the demands of small animation studios. The system will run in real-time on a regular workstation with standard specifications and will just require a single inexpensive camera for input. This method will enable the system to provide an affordable and available solution for hand motion analysis, enabling animation experts to produce realistic and captivating hand animations without the need for expensive hand tracking devices [3].

Clinical gait analysis is a noteworthy use of motion analysis [4]. Healthcare experts can analyse and assess people's gait patterns and biomechanics by using motion capture technologies. This helps in the diagnosis and treatment of ailments including musculoskeletal problems or neurological impairments that are connected to gait abnormalities. The accuracy and efficacy of clinical examinations have been considerably improved by the ability to properly measure and analyse movement characteristics, which has resulted in better patient outcomes. Motion analysis is crucial in the field of video game animation [5] for building believable and compelling virtual environments. Motion capture techniques are used by game producers to record the motions of actors or performers, which are subsequently converted into digital characters in the game. This makes it possible for the characters to display lifelike actions and behaviours, improving the user's game experience. The development of extremely interesting and aesthetically pleasing video game animations has greatly benefited from the development of motion analysis in this context [6].

The collection [7] of kinematic data in a variety of situations is made possible by direct motion analysis methods. Utilising inertial sensors, such as accelerometers, to understand how various movements are

carried out is one example. In order to analyse motion parameters including velocity, acceleration, and orientation angles, these sensors are mounted to the body and measure acceleration and orientation changes. Inertial sensors are suitable for use in sports science, rehabilitation, and ergonomics because they offer a discreet and portable way to record movement data [8]. Techniques for indirect motion analysis rely on vision-based methods. Video-based systems use one or more cameras to record the movement by taking pictures from various angles. To track the position and trajectory of body segments, optoelectronic systems use reflecting sensors or markers that are applied to the subject's body [9]. The 3D motion is recreated from the collected data by these devices using specialised software. High spatial resolution is provided by vision-based techniques, which are widely applied in fields including biomechanics research, animation, and sports performance evaluation [10].

III. Motion Analysis Techniques

Significant progress has been achieved in the study of biomechanics in recent decades, particularly in the creation of indirect, vision-based techniques for motion analysis. These techniques have made significant development, providing better automation and precision. A comprehensive tool that fully satisfies all the necessary requirements for motion analysis systems is still needed, though.

1. Manual digitised Technique:

For many years, manual digitization—often using cine film cameras with their high image quality and frame rates—was the most common method for measuring motion. However, because of the prolonged processing durations, this technique had limitations. Cine cameras became obsolete in the field of biomechanics with the development of video cameras, first tape-based and then later digital. Regardless of the motion capture technology used, manual digitization necessitates the time-consuming task of locating important points of interest, which frequently stand in for joint centres, in each frame recorded from various camera views. The positional information of the recognised points in the acquired images can be converted into real-world coordinates when a calibration trial is completed, which entails digitising known control points with known relative positions in each camera view. Common techniques for achieving this reconstruction include direct linear transformation [7]. Since no markers need to be attached to the subject's body, manual digitising provides the distinct advantage of enabling non-invasive data collecting. The ability to analyse movement during routine training sessions [8, 9] as well as competitive settings without affecting the athlete's performance makes manual digitising a valuable tool in sports biomechanics. The field of manual digitization is still relevant because of its flexibility and openendedness.

2. Automatic Marker-Based Systems

Systems that use computer vision algorithms to automatically track markers placed on the subject's body are known as automatic marker-based systems. Without the requirement for manual marker identification and tracking, these devices can accurately capture motion data. Automatic marker-based systems have the advantages of being able to deliver real-time data, increasing data gathering efficiency, and reducing the need for manual labour. These devices' simultaneous marker collection capabilities enable thorough study of joint angles and movement patterns. However, autonomous marker-based

systems might not be able to follow markers precisely during quick or obscured motions. They could also be sensitive to environmental elements like illumination. Furthermore, these systems' setup and calibration procedures can take a while and call for technical know-how.

Numerous fields, including sports biomechanics, clinical gait analysis, rehabilitation, ergonomics, and animation, use these systems. They help to understand how people walk in various circumstances and enable detailed kinematic analysis and movement pattern systems performed evaluation. By examining how well-known commercial marker-based on a rigid, rotating construction with markers at known positions, their accuracy was determined [10]. The analysis revealed that root mean square errors for markers in visible motion were frequently below 2.0 mm and 1.0 mm for stationary markers (scaled to a typical 3-meter volume). This shows superb accuracy when markers are fastened to a stiff body. However, it can be difficult to place markers precisely on anatomical landmarks, and markers positions to actual joint positions. When comparing marker positions to actual joint placements, soft tissue movement and skin artefacts might cause extra mistakes and inconsistencies.

3. Systems for Markerless Motion Analysis

Moving towards a totally autonomous, non-invasive markerless approach is a prospective future advancement in motion analysis. Such a development would signify a huge progress in sports biomechanics and rehabilitation research as well as in real-world applications. It would make it possible to analyse motion in typical training contexts without the human processing or time-consuming subject preparation needed by marker-based systems or more conventional techniques.

The inherent trade-off between accuracy (in laboratory-based studies) and external validity (in field-based analyses) that biomechanists frequently face might also be addressed by a markerless approach. This method has the potential to offer a solution that combines high accuracy and practical applicability by doing away with the requirement for markers and their accompanying drawbacks, improving comprehension and practical application of biomechanical concepts.



Figure 1: Structure of generative (green) and discriminative (orange) algorithms for markerless motion capture

Camera systems, body model representation, picture features, and parameter determination algorithms make up a markerless motion capture system. The standard illustration of the system's construction is shown in Figure 1.

- Camera Systems: To record the motion data, the system makes use of camera configurations. These cameras capture the subject's motions from numerous angles to give a complete picture.
- 2. Representation of Body Models: A 3D skeletal model of the human body is frequently used as a depiction of the human body. The joints, bones, and other pertinent anatomical structures are described in this model.
- 3. Image Features: The distinctive visual traits of the subject that were photographed by the cameras are referred to as image features. These features are taken out of the photos and sent into the algorithms for motion analysis.
- 4. Algorithms for Parameter Determination: The system uses algorithms to determine the body model's parameters, such as shape, pose, and position. These algorithms fall within the generative or discriminative categories. Generated hypotheses from generative algorithms are tested against image data and iteratively improved to achieve the greatest match. Contrarily, discriminative algorithms use the visual data to directly infer the model parameters.

A markerless motion capture system, in summary, comprises of camera systems for data collection, a model of the human body, picture features derived from captured images, and algorithms that establish the body model's parameters. Without the use of physical markers, these elements work together to provide accurate motion analysis.

Techniques	Details	Advantages	Limitation
Motion Sensors	Devices that measure	Real-time data capturing is	spatial resolution is limited
	acceleration and are	suited for portable,	and is susceptible to sensor
	attached to the body	unobtrusive devices.	drift
Marker-based	cameras or optoelectronics	Accurate spatial tracking for	requires careful marker
Systems	tracking reflective markers	in-depth study	placement and has a limited
			field of view
Visual-based video	Cameras capture	Flexible setup choices and	Low lighting and occlusions
Systems	movement for further	high spatial resolution	may cause limited accuracy.
	study.		
Electromyography	monitors muscle activation	provide insight into the	unable to record kinematics
(EMG)	when moving	patterns of muscle	and only capable of measuring
		activation	muscle activity
Kinect	Depth-sensing camera for	Non-intrusive, 3D motion is	Limited resolution and
	body movement tracking	captured	accuracy, sensitive to
			obstructions

Tabla 1. Cam			line to the share to the second		
Lable L: Com	nparing differei	it motion ana	ivsis techniqui	es pased on	various criteria

Pressure Sensors	Surface sensors that	Records ground response	limited to force distribution
capturing motion	monitor force distribution	forces and is useful for gait	measurement and requiring
		analysis.	certain surfaces

IV. Motion capture and Analysis Algorithm

1. Generative Algorithm

In motion capture analysis, generative algorithms also referred to as model-based algorithms are frequently employed to infer body model parameters from image data. These algorithms produce assumptions on the attitude, shape, and placement of the body in each frame using the body model and its related parameters. The parameters are then iteratively modified to get the best match when these hypotheses are compared to the picture data. In generative motion capture techniques, the stance and shape of a person are determined by fitting a body model to data collected from an image. During the fitting process, a model's body shape, bone lengths, and joint angles are used to create a representation of the model.

After comparing the generated representation to the features that were retrieved from the image, a "error value" that measures the discrepancy between the hypothesis and the observed data is produced. Projecting the 3D triangle mesh created from the predicted parameters onto the 2D image is one method of computing the error value. By doing this, it is possible to maximise the overlap between the mesh and the figure's silhouette [92]. Generative motion capture techniques seek to improve the alignment between the generated model and the observed data by reducing the error value through an iterative optimisation process. For applications like character animation, virtual reality, and human-computer interaction, this makes it possible to estimate the person's pose and shape from the image.

It's vital to remember that this description just provides a condensed overview of generative motion capture methods; several techniques and algorithms are used throughout this framework. Although the specifics and implementations may differ, the general objective is always to fit a body model to image data and iteratively improve it to produce a more accurate depiction of the person's stance and shape.

In motion capture analysis, the following generative methods are frequently employed:

- Iterative Closest Point (ICP): This algorithm minimises the distance between the body model and the relevant features in the images to iteratively align the body model with the observed image data.
- Particle Filters: Particle filters use a collection of particles, each of which stands for a potential pose and shape of the body. The best-fitting parameters are computed after these particles are propagated and weighted based on their consistency with the observed image features.
- Optimisation Techniques The parameters of optimization-based algorithms are determined by minimising an objective function, which is a representation of the difference between the created body model and the observed picture data.

• The body model's parameters are updated by Kalman filters, which use a recursive estimating strategy.

The advantage of generative algorithms is that they can incorporate previous understanding of the body model, enabling more precise and reliable parameter estimates. They can be computationally demanding, though, and they can be susceptible to setup and tracking mistakes. They are also better suited for offline analysis than for real-time applications due to their iterative nature.

2. Discriminative Approach

Motion capture analysis discriminative methods can be divided into two types. One method entails directly mapping image data to position descriptions, frequently using regression approaches based on machine learning [13]. In this way, a simplified skeleton model's pose can be determined by the computer using only image data. Recent developments in this strategy use deep learning techniques to train systems that can recognise bodily parts, infer joint ownership, and effectively parse this data to determine skeletons [12]. The most comparable known stance based on the present image can be found instead by searching a database of pose samples. Previous research [14, 15] have used this methodology. The system can identify the most appropriate pose by comparing the current image to the pose samples in the database.

The discriminative approaches in motion capture analysis either rely on a pose database for comparison to determine the most similar known pose, or direct mapping from picture attributes to pose descriptions using machine learning-based regression. These methods make use of recent deep learning developments and enable automated pose estimation right from visual data.

It's crucial to remember that the specific implementation, the quality and variety of training data, the complexity of the motion being analysed, and other factors might affect the performance and characteristics of discriminative methods and generative algorithms. This table offers a broad comparison to emphasise some significant differences between the two strategies as discussed in table 2.

Sr No	Parameter	Discriminative Method	Generative Method
1	Approach	Direct mapping of posture to picture attributes	Use a body model and come up with theories
2	Training	Labelled training data are required for tasks involving regression or classification.	Need a body model and starting conditions
3	Real-time performance	can be implemented to attain real- time performance	Usually slower as a result of iterative improvement
4	Flexibility	Training data and model representation limitations	Considering past body model knowledge

Table 2: Comparative study of generative and discriminative algorithms for motion capture analysis

5	Accuracy	heavily reliant on the calibre and	high rigid structural correctness,
		variety of training data	sensitive to tracking and startup
			issues
6	Robustness	Adaptable to changes in image quality	Resilient to occlusions, noise, and
		and subject appearances	non-rigid deformations
7	Computational	can be computationally effective,	
	Efficiency	especially when implemented with	requiring a lot of computation
		optimisation	because iterative refinement

Table 3: Overview of works contrasting traditional motion analysis systems with markerless systems

Movement	Camera System	Motion Capture	Number of	RMS Differences
		System	Subjects	
Starjump,	Gen-locked video	Manual digitising	3	Pelvis location: 10-30 mm,
somersaults	cameras (50 Hz)	(TARGET system)		Body configuration angles: 2°-
				8°
Walking	Visual hull	Virtual environment	16	Hip, knee, ankle angles: 2.0°-
	construction and a	(Poser software)		9.0°
	priori subject-			
	specific model			
Walking	Video cameras (75	Qualisys (120 Hz)	8	Knee joint angle deviation:
	Hz), visual hull			2.3° (sagittal), 1.6° (frontal)
	construction and a			
	priori subject-			
	specific model			
Walking	Video cameras (120	Qualisys (120 Hz)	8	Deviations between joint
	Hz), visual hull			centres: 15 mm (mean
	construction and a			absolute error)
	priori subject-			
	specific model			
Reaching,	Microsoft Kinect (30	Motion Analysis	1 Kinect, 12	Maximum abduction error:
throwing,	Hz)	Corporation (60 Hz)	optoelectronic	44.1° (NITE tracking), 13.9°
jumping				(IPIsoft tracking)
Walking	BTS SMART-D (100	BTS SMART-D (200	8	Maximum RMS differences:
	Hz)	Hz)		11.0°-34.7°
Walking	Monochrome	Ariel Performance	8	RMS differences in lower limb
	cameras (75 Hz),	Analysis System		3D angles: 1.8°-4.9°
	unconstrained			
	articulated model fit			
	to 3D point clouds			

Walking and	Point Grey cameras	Motion Analysis	2 markerless, 8	RMS differences: 0.2°-1.0°
jogging	(25 Hz)	Corporation (100 Hz)	marker-based	(significant differences in
				ankle joint angles)

V. Conclusion

In this study, we looked into motion analysis methods for animation assessment and development. As opposed to the subjective judgements of animators and directors, these methodologies provide objective measurements to evaluate the calibre and realism of animated motion. Motion analysis highlights specific areas of concern, gives accurate and quantifiable data, and helps to optimise the pipeline for creating animated films. While portable and unobtrusive direct methods, like inertial sensors and marker-based systems, are available, indirect methods, like video-based systems and optoelectronic systems, offer high spatial resolution and accurate tracking. The choice of approach depends on the particular requirements of the application because each technique has advantages and disadvantages. By fitting body models to image data, generative motion capture techniques have showed promise in identifying the position and shape of animated creatures. These methods improve the accuracy of character animation by optimising model parameters and increasing the overlap between the model and the silhouette in the image. Techniques for motion analysis have evolved into crucial tools for assessing and improving animation. We have learned more about these methods' advantages, disadvantages, and uses as a result of our inquiry. More advanced and effective motion analysis techniques will be made possible by ongoing research and development in this area, giving animators and other industry experts the tools they need to produce aesthetically appealing and lifelike animations.

VI. Future Direction

There are a number of possible future possibilities for the study and creation of motion analysis methods for the assessment and enhancement of animation:

Machine learning advancements: By enabling automated pattern recognition, predictive modelling, and data-driven animation enhancements, the combination of machine learning and deep learning techniques can improve motion analysis.

Real-time Performance: Additional research should concentrate on creating real-time motion analysis tools that can give animators direct feedback while the animation is being created, allowing for iterative improvements and quicker turnaround times.

Exploring hybrid motion analysis methods that combine the benefits of many methodologies, such as combining information from inertial sensors and vision-based systems, can result in motion capture and evaluation methods that are more reliable and accurate.

Applications that cross domains: Using motion analysis methods that have been established for one domain, such as sports or clinical situations, in other domains, such as gaming, virtual reality, or robotics, can promote innovation and idea-sharing.

Accessibility and Affordability: In order to enable a wider spectrum of creators to gain from unbiased motion evaluation and improvement, efforts should be made to make motion analysis tools and systems more accessible and affordable for small animation studios and individual animators.

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